

Implementing arrays for fault detection in R software

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Goal: implement an R package that provides covering arrays (CAs) with the most important tools around them

I am new to that field.

I will share my fresh insights on CAs:

- \blacksquare their usage,
- \blacksquare algorithms for creating them,
- quality criteria,
- \blacksquare practical aspects,

and my thoughts regarding implementation.

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Test situation

Assumption: a system under test (SUT) whose behavior is driven by *m* factors F_1, \ldots, F_m , where F_i has s_i levels v_{i1}, \ldots, v_{is_i} .

The test suite *D* consists of *N* test runs, i.e., *N* particular level combinations of the *m* factors.

For each test, the outcome is a "pass" or a "fail".

We will assume that - in the absence of mistakes - the same test run would yield the same outcome again and again (e.g., in software testing), i.e., testing itself is deterministic.

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Faults can be caused by pairs, triples, quadruples, … of factors.

Interaction Rule: Most failures are induced by single factor faults or by the joint combinatorial effect (interaction) of two factors, with progressively fewer failures induced by interactions between three or more factors. Kuhn et al. (2010)

Different questions:

Is the product fault-free?

sufficient to pass all runs of certain coverage quality (e.g., all value pairs or all value triples) \rightarrow Covering Arrays

■ What conditions lead to faults?

more difficult, distinguishing different potential candidates required

- either engineering judgment combined with subsequent confirmation experiments permitted
- or experiment that directly leads to identification of failure root causes (further types of arrays)

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An ℓ way interaction is an ℓ -dimensional value combination for ℓ factors, i.e., e.g.,

- $A=0, B=0$
- $A=1, B=0$
- $A=0, B=1$
- A=1, B=1

are four 2way-interactions (2IAs).

A **C**overing **A**rray (CA) of strength *t* is a test set (=experimental design) *D* for which each *t*IA appears at least once.

Notation:

- $CA(N, t, m, s_1^{m1} ... s_k^{mk})$ $\binom{mk}{k}$ with $m_1 + \cdots + m_k = m$, $CA(N, t, m, (s₁, ..., s_m)),$
- \blacksquare CA(*N*, *t*, *m*, *s*) (uniform arrays)

Orthogonal array (OA) vs. CA of strength *t*:

OA requires each *t*IA for a given *t*-tuple of factors to appear **the same number** of times;

"**at least once**" (CA) is much less demanding.

Example

six factors with 2,2,3,5,7,8 levels strength $t = 2$:

Total number of 2IAs to be covered

$$
\sum_{i=1}^{5}\sum_{j=i+1}^{6}s_{i}s_{j} = 287
$$

3360 runs – Full factorial (reference) 1680 runs – OA 56 runs – CA (7 \cdot 8 = 56)

We can save even more runs by using many more 2-level factors in those 56 runs (at least 600 2-level factors are possible, see also below).

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An example CA *D* **(a CA**(56, 2, 6, (2, 2, 3, 5, 7, 8))**)**

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Usage principle

- Sets $\mathcal F$ and $\mathcal P$ hold *t*IAs that occur in failed runs or passed runs, respectively.
- Potential Failure Generating 2IAs are those in $\mathcal{F} \mathcal{P}$.

Examples with design *D* (CA(56, 2, 6, (2, 2, 3, 5, 7, 8)), $t = 2$):

- all runs passed: no failures from 2IAs
- Run 10 failed, all others passed: There is only a single 2IA in $\mathcal{F} \mathcal{P}$. namely levels of factors 5 and 6 both equal to 1. Thus, the 2IA is uniquely identified.
- Run 36 failed, all others passed: There are three 2IAs in $\mathcal{F} \mathcal{P}$. namely factor 4 level 0 with factor 5 level 4, factor 4 level 0 with factor 6 level 3,
	- factor 5 level 4 with factor 6 level 3

For non-unique answers, engineering judgment or further experimentation can help.

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Table 2: Coverage behavior of the two 56 run CAs (in pct))

- irritating that CA $(56,2,604,2^{600}3^15^17^18^1)$ looks better on the quality criteria than CA $(56, 2, 6, 2^23^15^17^18^1)$
- **u** usability for identifying fault-generating IAs would be of interest (LAs, DAs)

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- **a** approaches for creating CAs
- practical aspects
- thoughts on the planned project

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Strategies

- mathematical methods for uniform CAs (e.g., Torres-Jimenez et al. (2019)) and (fewer) for mixed level CAs (e.g., Akhtar et al. (2024))
- search algorithms, as, e.g., described in Leithner et al. (2024)
	- \blacksquare IPO = in parameter order:
		- \blacksquare starts with an array in the first *t* columns,
		- \blacksquare extends it horizontally with further columns,
		- \blacksquare and where necessary vertically with further rows
		- various variants ((F)IPOG, (F)IPOG-F, (F)IPOG-F2)
	- \blacksquare OTAT = one test at a time:
		- \blacksquare add tests one at a time.
		- maximize the number of additionally covered *t*-way interactions with each additional test (greedy)
	- metaheuristics and postoptimization
		- tabu search
		- simulated annealing
		- \blacksquare optimizing (=reducing the number of tests) an existing array with one of these methods

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Software

- **CAgen** (by an Austrian team around Dimitris Simos, Wagner et al. (2020), https: //srd.sba-research.org/tools/cagen/#/help; FIPOG, FIPOG-F, FIPOG-F2),
- **CTwedge** (by an Italian team from Bergamo, Gargantini and Radavelli (2018))

typically handle constraints,

these two offer free web versions.

Further software, e.g.

- allpairspy (Python package) by Hombashi (2023)
- **JMPPro implementation (JMP Statistical Discovery LLC (2024)),** commercial, free access for students and academics

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The catalogues cover uniform arrays only:

- **NIST catalogue of CAs:** 21 964 **actual arrays** for strengths 2 to 6, 2 to 6 levels, and up to 2 000 columns, size up to 125 683 runs ("NIST Covering Array Tables" (n.d.); arrays are downloadable as zip-files)
- Table of smallest possible sizes (Colbourn (n.d.)), **without the actual arrays** but with, somewhat cryptic, references; 13 641 entries, strength 2 to 6, for 2 to 25 levels, and up to 10 000 columns; still 2 884 entries for up to 6 levels, with size up to 13 759 798)

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Uniform arrays will rarely suffice!

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It will often not be possible or desirable to accommodate all level combinations.

- \blacksquare a certain level combination is technically incompatible
- a certain level combination is not sold for other reasons

It can also happen that there is not a single valid level for a factor, which is called **unsatisfiable constraint** (e.g., in JMP, see next slide).

u

Unsatisfiable constraints (created with JMPPro)

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Don't care values (created with CAgen)

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are useful during design creation

- \blacksquare for high expandability
- \blacksquare for potential optimization of quality metrics

 \sim …

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It might be of interest to have varying strength requirements for different subsets of factors in the SUT.

e.g. uniform array of relatively high strength for many factors with few levels, combined with a few factors at more levels (added with a lower strength requirement).

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- The catalogue "NIST Covering Array Tables" (n.d.) of Tables of reasonably small (IPOG-F generated) uniform CAs $(s = 2, ..., 6, t = 2, ..., 6$ without $s = 6$ with $t = 6$);
- \blacksquare the Colbourn tables in conjunction with review papers on mathematical algorithms, e.g. Torres-Jimenez et al. (2019)
- papers on mathematical algorithms for mixed CAs (e.g., Akhtar et al. (2024))
- open source Python code for possibly transferring

Helpful for comparisons:

free CA generation tools

- CAgen web, CAgen CLI (free academic use on request)
- CTwedge web (free),
- **JMPPro (free academic use)**

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- Tables provide combinations of *k*, *t*, *s*, *N* plus some reference, e.g. "Cyclotomy (Colbourn)"
- **Cyclotomy** construction (Colbourn or otherwise) is behind 183 of the 2884 entries for up to 6 levels (6.35%)
- Colbourn (2010) provides several related constructions (1, 2, 3, 3a, 3b, 4, 4a, 4b) around cyclotomic start vectors (based on Galois field logarithms).

Current state:

- \blacksquare figured out which construction for which entry
- created several arrays and confirmed their coverage properties

Expectation:

- **nost of these arrays can be created**
- **Creation is fast, even for large arrays**

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- whether or not a construction yields a CA for a given prime or prime power can only be decided by **combinatorial checks** of relatively complicated conditions (mathematically proven general bounds way too large)
- these are still much **much less demanding than checking coverage brute force**;

e.g., a brute force full check of strength 4 coverage a CA $($ 1051 $,$ 4 $,$ $3^{1051})$ took 3.5 hours on a powerful machine with 30 parallel threads.

 \blacksquare checks are needed, if only for programming mistakes; current strategy for routine checks: sampling subgroups of columns

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Example continued: Cyclotomy constructions

Example continued: Cyclotomy constructions

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Thoughts on planned project

- **Implement** *mathematical* algorithms for good uniform CAs, based on Colbourn tables (sounds easier than it is)
- \blacksquare These can be building blocks for more practically relevant arrays.
- \blacksquare Implement mathematical algorithms for mixed level CAs
- \blacksquare It might be worth while to try and supplement the Colbourn tables with actual arrays and/or pseudo codes of algorithms.
- \blacksquare Identify and implement useful algorithms for extending uniform arrays with a few different columns?
- \blacksquare Is it worth while for applications to implement LAs and DAs?
- Resource-intensive search tools can possibly be accessed via an API from R (e.g., the command line interface of CAgen, which is, however, not freely available for everybody)
- \blacksquare Are there real-world good practice examples for my benefit focusing on usage of CAs (LAs, DAs) rather than the entire software testing cycle ?

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Any advice is highly appreciated.

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